

Stochastic Navier–Stokes equations via convex integration

Xiangchan Zhu

Chinese Academy of Sciences

Introduction

Introduction

Consider the Navier-Stokes equation on \mathbb{T}^3 :

$$\begin{aligned}\partial_t u + u \cdot \nabla u &= \nu \Delta u - \nabla p + \xi, & \operatorname{div} u &= 0 \\ u(0) &= u_0\end{aligned}\tag{1}$$

- $u(t, x) \in \mathbb{R}^3$: the velocity field at time t and position x ,
- $p(t, x)$: the pressure,
- $\nu > 0$: the viscosity constant
- ξ : trace-class noise

Derivation of Navier-Stokes system: Newton's law

Suppose $u = u(t, x(t))$ and ρ : the density

$$\frac{d}{dt}u(t) = \underbrace{\partial_t u}_{\text{variation}} + \underbrace{u \cdot \nabla u}_{\text{convection}} = \underbrace{\nu \Delta u}_{\text{Diffusion}} - \underbrace{\nabla p}_{\text{Internal source}} + \underbrace{f}_{\text{External source}},$$

$$\underbrace{\partial_t \rho + \nabla \cdot (\rho u)}_{\text{mass conservation}} = 0 \Rightarrow \text{if } \rho = \text{constant} \text{ } \operatorname{div} u = 0$$

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Motivation of Gaussian noise

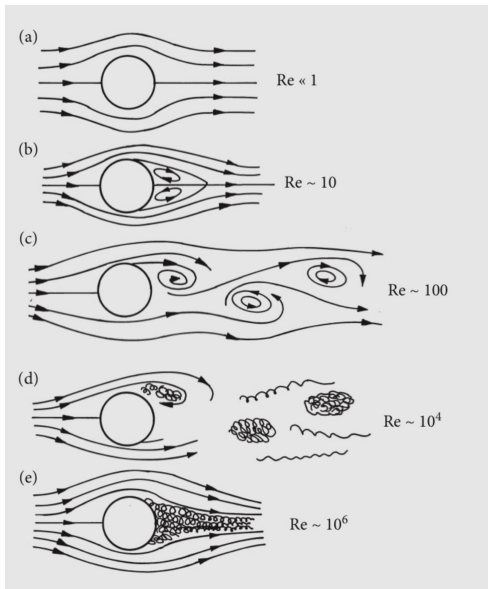
- stochastic reduction
- regularization by noise
- turbulence **Kolmogorov ('41) theory**

Zeroth law of turbulence: the inviscid limit $\nu \rightarrow 0$

$$\varepsilon = \liminf_{\nu \rightarrow 0} \left(\nu \langle |\nabla u_\nu|^2 \rangle \right) > 0,$$

$\langle \cdot \rangle$: integration w.r.t. spatial variable and stationary measure μ^ν

Kolmogorov ('41) theory: 2/3 law, 4/5 law.



$$\partial_t u + u \cdot \nabla u = \nu \Delta u - \nabla p + \xi, \quad Re \sim 1/\nu$$

Introduction

Deterministic: [Leray34], [Kato, Fujita62], [Temam84], [Constantin, Foias88] [Cafarelli, Kohn, Nirenberg84], [Fefferman 00], [Koch, Tataru01], [Zhang],...

- The global existence of **weak** solutions has been obtained in all dimensions.
- Existence and smoothness of solutions in the three dimensional case remains open (**the Millennium Prize problem**)./ Small initial data
- [Buckmaster, Vicol AOM19]: Non-uniqueness of analytic weak solutions
- [Albritton, E. Brué, M. Colombo. AOM22] non-uniqueness of Leray solutions for some force

Naiver-Stokes equations driven by trace-class noise

Different notions of solutions

- Martingale solutions/Probabilistically weak solutions: probability measure on the canonical space $C([0, \infty) : H^{-3})$
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Known result:

- Leray martingale Markov solutions to stochastic 3D Navier-Stokes have been constructed [Flandoli, Romito PTRF08]

Convex integration for N-S

- Convex integration: iteration procedure a pair (v_q, \mathring{R}_q) is constructed solving the following system

$$\partial_t v_q - \Delta v_q + \operatorname{div}(v_q \otimes v_q) + \nabla p_q = \operatorname{div} \mathring{R}_q \quad \operatorname{div} v_q = 0.$$

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- Key step: Let $w_{q+1} = v_{q+1} - v_q$, then we have

$$\begin{aligned} \operatorname{div} \dot{R}_{q+1} = & \underbrace{-\Delta w_{q+1} + \partial_t w_{q+1} + \operatorname{div}(v_q \otimes w_{q+1} + w_{q+1} \otimes v_q)}_{\text{linear error}} \\ & + \underbrace{\operatorname{div}(w_{q+1} \otimes w_{q+1} + \dot{R}_q)}_{\text{oscillation error: cancellation}} + \nabla p_{q+1} - \nabla p_q. \end{aligned}$$

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$w_{q+1} \sim \sum_{\xi} a_{\xi}(\dot{R}_q) W_{\xi}$, where W_{ξ} is intermittent jets/Beltrami waves/Mikado waves.

- The space concentration ensure the linear error is small in L^1
- $\int W_{\xi} \otimes W_{\xi} \simeq 1$ and $a_{\xi}(\dot{R}_q) \approx \sqrt{-\dot{R}_q}$ oscillates slowly

Nonuniqueness in law for Stochastic 3D Navier-Stokes/Euler equations

Problem 1: Non-uniqueness in law hold?

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① Regularization by noise:

- The ODE

$$dX_t = |X_t|^\alpha dt, \quad X_0 = 0, \quad \alpha \in (0, 1)$$

has infinitely many solutions

- The SDE

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$$dX_t = \text{sign}(X_t)dB_t$$

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Theorem (Hofmanová, Zhu, Z. 19/ CPAM22)

Non-uniqueness in law holds for the stochastic 3D Navier- Stokes/ Euler system.

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- [Chen, Dong, Z. 22] Sharp nonuniqueness and global probabilistically strong solutions in higher dimensions/ Euler equations
 - [Lü, Z. 22] Global probabilistically strong solutions for power law equations

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- basic assumption in turbulence theory:

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Known result:

- 2d Navier-Stokes: Uniqueness of invariant measure [[Hairer, Mattingly AOM06](#)]
- 3d Navier-Stokes with non-degenerate noise: Every Markov selection has a unique invariant measure [[Flandoli, Romito PTRF08](#)]

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Theorem (Hofmanová, Zhu, Z. 22)

There exist

- 1 *infinitely many stationary solutions;*
- 2 *infinitely many **ergodic stationary** solutions;*

to the stochastic 3D Navier–Stokes and Euler equations.

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For any $\nu_n \rightarrow 0$, \exists stationary solutions u_n to SNS with $\nu = \nu_n$ so that $\mathcal{L}[u_n]$, $n \in \mathbb{N}$, is tight in $C(\mathbb{R}; L^2_\sigma)$ and every accumulation point is a stationary solution to the stochastic Euler equations.

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Idea of proof: Stochastic convex integration

$$\sup_{\nu} \sup_{s \in \mathbb{R}} (\mathbf{E} \sup_{s \leq t \leq s+1} \|u(t)\|_{H^\vartheta}^2 + \mathbf{E} \|u(t)\|_{C^\vartheta([s, s+1]; L^2)}^2) < \infty.$$

Anomalous dissipation

Theorem (Hofmanová, Zhu, Z. 22)

For any $\epsilon > 0$, $\exists \nu_n \rightarrow 0$ and stationary processes $(u_n, \dot{R}_n) \in C(\mathbb{R}; H^1) \times C(\mathbb{R}; L^1)$ satisfying the following stochastic Navier–Stokes–Reynolds equations

$$du_n + \operatorname{div}(u_n \otimes u_n) dt + \nabla P_n dt = \nu_n \Delta u_n dt + \operatorname{div} \dot{R}_n dt + dB,$$

$$\lim_{n \rightarrow \infty} \mathbf{E} \left[\sup_{0 \leq s \leq 1} \|\dot{R}_n(s)\|_{L^1} \right] = 0,$$

and

$$\liminf_{n \rightarrow \infty} \nu_n \mathbf{E} \|\nabla u_n\|_{L^2}^2 \geq \epsilon + \frac{1}{2} \operatorname{tr}(GG^*).$$

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$$\liminf_{n \rightarrow \infty} \nu_n \mathbf{E} \|\nabla u_n\|_{L^2}^2 \geq \epsilon + \frac{1}{2} \operatorname{tr}(GG^*).$$

Furthermore, the laws $\mathcal{L}[u_n]$, $n \in \mathbb{N}$, is tight in $C(\mathbb{R}; L^2_\sigma)$ and every accumulation point is a stationary solution to the stochastic Euler equations.

see [Brue, De Lellis 22]

Thank you !